

Virtual Measurement of the Backlash Gap in Industrial Manipulators





Topic

- Industrially focused research problem
- Industrial manipulator
- Gears aeging Backlash phenomenon
- Predictive maintenance
- Virtual sensor
- lot



Goal

<u>Translate</u> a <u>disturbance identification/carachterization problem</u> in an <u>optimization problem</u> well suited for CI techniques



Easy solution for a N-variables non-separable problem



Virtual sensor realization

Innovation

- Industrial standard solutions:
- Sensors placed close to the expected fault location
 - Accelerometer
- Two encoders (motor + load encoder)



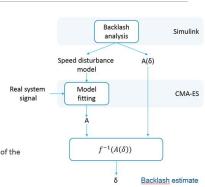


- New solution:
- Sensors NOT close to the fault location
- No dedicated sensor
- Motor encoder only → virtual sensor



Method

- Backlash analisys of a robotic joint transmission
- System and phenomenon modeling
- Estimate from indirect measuring methods
- Value prediction over time
- Tools
- Matlab/siumlilnk
- Python CMA-ES
- Method validation
- Performance analisys: comparison of real measured values with the output of the developed algorithm
- Applicability limits
- Method generalization



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